

# DeMeMech-Exchange Presentation

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Genetic Programming is an evolutionary search algorithm much like Genetic Algorithms

It automatically finds solutions to a before specified problem

Difference to GA: GP produces <u>computer programs</u> as solutions

Classical GP produces programs with tree-structure called parse trees. The algorithms generates those trees by randomly choosing from a set of functions and terminals (non-terminals = nodes, terminals=leafs)



#### Construction of programs in GP

Initially a fixed number of such programs (a generation) is generated

Then every program is executed and a fitness is assigned which reflects how well the program accomplished the task

#### **Cross-over operation**

The cross-over operation is performed by taking subtrees of two parent programs and then exchanging those trees



#### **Point-mutation**

The point-mutation is performed by choosing a random node or leaf and changing it.



#### Subtree-mutation

The subtree-mutation is performed by choosing a random subtree and substituting it with another.



### Construction of new ADFs



Source: <u>http://www.genetic-programming.com</u>/

### **Branch duplication ADFs**



Source: <a href="http://www.genetic-programming.com/">http://www.genetic-programming.com/</a>

The process of generating and evaluating new program generations is repeated until a satisfying solution is found

- Recently GP has evolved new solutions for problems like electronic circuit design, quantum computing algorithms or optical lens system design
- This is due to the exponentially growing computing power and GP solutions often involved large clusters of computers (1000-node-clusters for example)

## Initial goal of this research

Use GP to derive a program for cooperative RoboCup Soccer Robots (4-legged league)

## Initial goal of this research

Existing code would allow construction of parse trees with little modification
Use simulator to coevolve soccer teams using existing high-level functions

GP is able to create simple solutions but fails to produce more complex solutions

This is because by increasing the program size linearly the search space grows exponentially Exponentially more programs with non-functional code

Number of lines of hand-coded program with equal functionality to so far best GP program



Increasing GP program size

This exponential grows in possible programs can be called the "curse of dimensionality"

Therefore new ways to find useful programs with greater complexity have to be found, i.e. we have to restrict the search space to areas with possibly useful solutions without limiting it so much that the power of the evolutionary mechanism is lost

**Concerning the initial goal:** 

Several attempts for using GP to derive soccer players for the Simulation League have been made, including evolution of homogeneous and heterogenous teams, multiple-goals fitness and competitive coevolution but the found solutions often show less complex behavior called "kiddie soccer"



Increasing complexity of behavior

GP consists of the following problem areas:

- 1. Terminal and Function set
- O 2. Fitness function
- 3. Construction of program

Terminals and function sets have been extensively researched as in automatically defined functions (ADFs) or macros(ADMs)

Idea: Improve the fitness function

Instead of having one fixed fitness function apply several fitness functions that compare the structure of the generated programs with the structure of handmade example programs using a metric measuring how similar the functionalities are

- Problem: Functional metric for tree structures
- Computational metrics can't measure functionality or their computation is exponential and therefore not applicable
- Use a measure that compares the output of example programs with those of the programs using the same inputs

Experiment:

Modification of TGP-code by Michai Oltean

Example-based fitness functions: Symbol Regression of a 10th-degree polynomial using lower-degree factors as example-functions

- Usage of previous solved solutions as ADFs in the next case
- Global elitist approach with cross-over rate of 20% and 5% mutation
- 100 individuals per generations, 100 generations, 10 fitness functions, 10 sample-data, 100 runs
- Compare to classical GP with ADFs

- Results of experimenting on a symbolic regression problem showed no improvement to GP with ADFs.
- Conclusion: Either the given problem (symbolic regression) was too simple to be broken down to subtasks or the power of possible subtask accomplishment is annulled with the cross-over and mutation actions. These are believed to destroy previously found solutions to subtasks when a new fitness function is used
- Need for preserving functional entities

### Grammatical construction of GP

## Since the improvement of the fitness function seemed not general and unfruitful

Improve the construction of programs in GP



Improve the structure of programs in GP

### Grammatical construction of GP

Use/evolve context-free grammars who should construct programs

Grammars in this context are considered to be production rules for valid expressions

**Production rules** 

Example application

 $S \rightarrow Bcc$   $A \rightarrow Aa$   $A \rightarrow a$   $S \rightarrow Bcc \rightarrow Abcc \rightarrow Aabcc \rightarrow aabcc$  $B \rightarrow Ab$ 

### Grammatical construction of GP

Production rules are evolved which restrict the space of possible solutions

- Solutions are constructed with these rules which then are tested
- Reason for this approach: Possibly smaller dimension of search space for production rules then due to more abstract nature of production rules
- Approach of using grammars has already been applied with competitive but not superior performance

### Molecular program construction

Idea:

To reduce the destructive power of crossover and to prevent bloat, see genetic programs as collection of terminals and functions much like atoms with certain binding energies between them and maximize the energy to construct programs out of this configuraition

#### Table for binding energies between the components of the collection

	Fun1	Fun2	Fun3	Fun4	Fun5	Cons t1	Cons t2	Cons t3	Input 1	Input 2	Input 3	Input 4
Fun1			1	11			36		25		3	
Fun2	5	9		7								42
Fun3		7				62	3		6			23
Fun4			34	7				44	5	86	6	
Fun5				4	6	77			16			3
Const1												
Const2												
Const3												
Input1												
Input2												
Input3												
Input4												

### **Molecular program** construction

### Molecular program construction

Crossover operation would then simply be an exchange of components and mutation would also just be a replacing of certain components

The matrices would also be evolved and used to construct programs by optimizing the reward function

It is to be seen how effective a construction like this would be in means of computing necessary

### Molecular program construction

Every matrix would be assigned a certain amount of component sets to construct programs out of them

Those in turn would be evaluated and the average fitness would be assigned to the matrix

Then the matrices and the sets of components would undergo the evolutionary mechanisms and generate the next generation of matrices and sets

### Impression of Japan

#### Cherry-blossom parties

#### Robot everywhere



### Impressions of Japan



#### Making and eating soba



#### Yakiniku- Korean bbq



#### Suburban desert - never ends



#### Crazy video game devices

**Guitar Freak** 

#### Rollercoasters through buildings

## <u>...and of course Karaoke</u>