

# Summary

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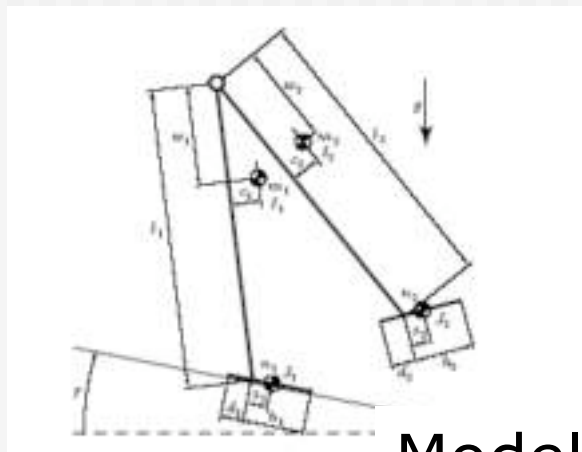
## Osaka University

Hidenori Fujii

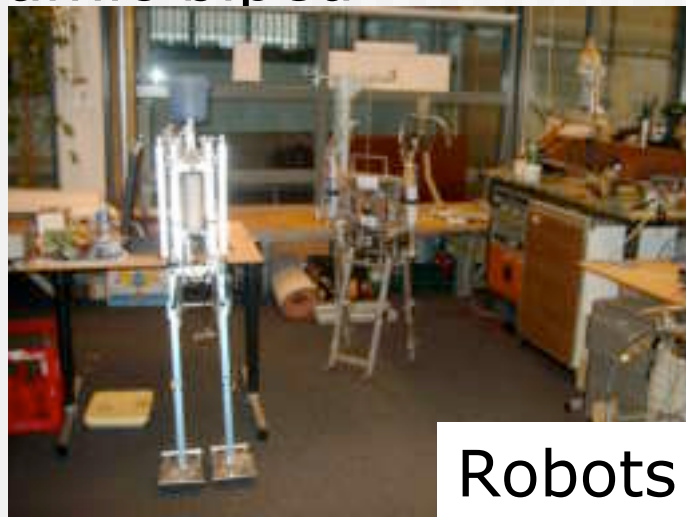
- Intercultural communication
- Lectures different from Japanese
- To get to know foreign students
- English conversation skill

# Research

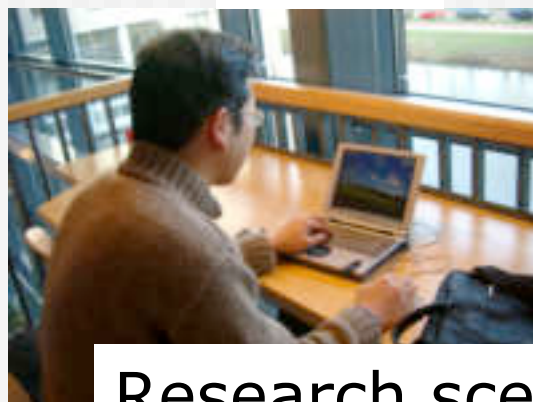
## Ankle actuation for dynamic biped



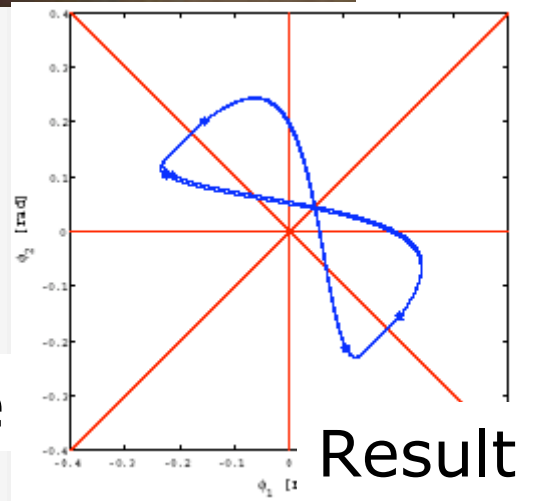
Model



Robots



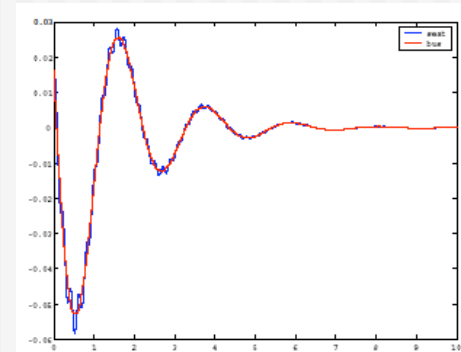
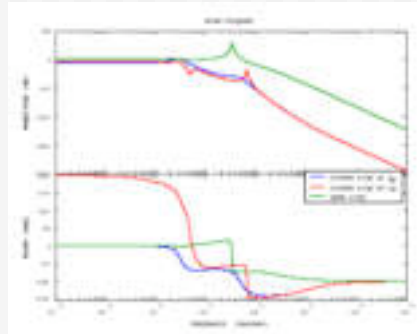
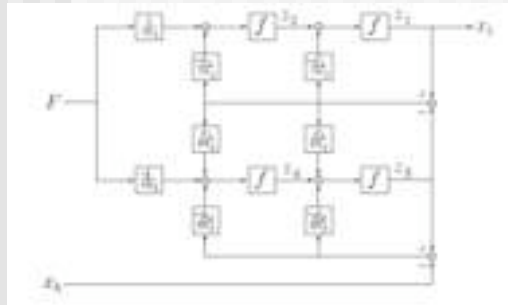
Research scene



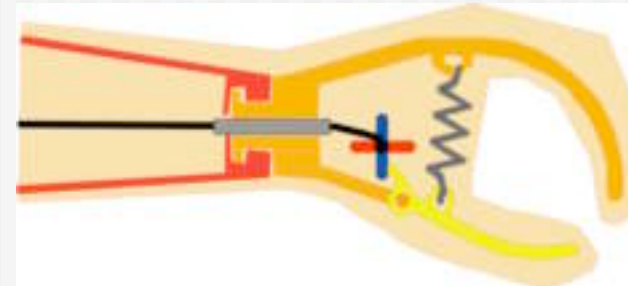
Result

# Lectures

- Control Theory(assignment)



- Biomedical Engineering Design(design of prosthesis)



- Optimization in system and control

# Exchange student life

